MTi-680G

- **Rugged, IP68 rated RTK GNSS/INS**
- **0.2 deg roll/pitch & sub-meter level position accuracy**
- **u-blox ZED F9 RTK GNSS receiver**

The MTi-680G is a Global Navigation Satellite System/Inertial Navigation System (GNSS/INS) with integrated Real-Time Kinematic (RTK) receiver, with a rugged housing with IP68 protection. The RTK feature improves your positional data from meter-level to centimeter-level accuracy. This easy-to-use RTK-enhanced GNSS/INS module is designed for seamless integration with other equipment.

The MTi-680G is supported by the MT Software Suite, which includes MT Manager (GUI for Windows/Linux), SDK, example codes and drivers for many platforms.

40.90 mm

56.50 mm

36.75 mm

- White label and OEM integration options available
- 3D models available on request
- Available online via Digi-Key, Mouser, Farnell and local distributors

Sensor Fusion Performance

Roll, Pitch	0,2 deg RMS
Yaw/Heading	0.5 deg RMS
Position	1cm CEP
Velocity	0.05m/s RMS

Gyroscope

Standard full range	2000 deg/s
In-run bias stability	8 deg/h
Bandwidth (-3dB)	520 Hz
Noise Density	0.007 º/s/√Hz
g-sensitivity (calibr.)	0.001 º/s/g

Accelerometer

Standard full range	10 g
In-run bias stability	10 (x,y) 15(z) µg
Bandwidth (-3dB)	500 Hz
Noise Density	60 µg/√Hz

Magnetometer

Standard full range	+/- 8 G
Total RMS noise	1 mG
Non-linearity	0.2%
Resolution	0.25 mG

RTK GNSS Receiver

Brand	u-blox
Model	ZED F9
RTCM input port	RTCM 3.3, RS232

Barometer

Standard full range	300-1250 hPa
Total RMS noise	1.2 Pa
Relative accuracy	+/- 8 Pa (~0.5m)

Mechanical

IP-rating	IP68
Operating Temperature	-40 to 85 ºC
Casing material	Aluminum
Mounting orientation	No restriction, full 360º in all axes
Dimensions	56.50x40.90x36.75 mm
Connector	Main: ODU (AMC HD 12 pins)
	RTCM: ODU (AMC HD 4 pins)
	Antenna: SMA
Weight	98 g

Electrical

Input voltage	4.5 to 24V
Power consumption (typ)	<1 W

Interfaces / IO

Interfaces	CAN, RS232
Sync Options	SyncIn, SyncOut, ClockSync
Protocols	Xbus, ASCII (NMEA) or CAN
Clock drift	1ppm
Output Frequency	2 kHz, 400 Hz SDI
Built-in-self test	Yes

Software Suite

GUI (Windows/Linux)	MT Manager Firmware updater, Magnetic Field Mapper
SDK (Example code)	C++, C#, python, Matlab, Nucleo, public source code
Drivers	LabVIEW, ROS, GO
Support	BASE by XSENS: online manuals, community and knowledge base

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